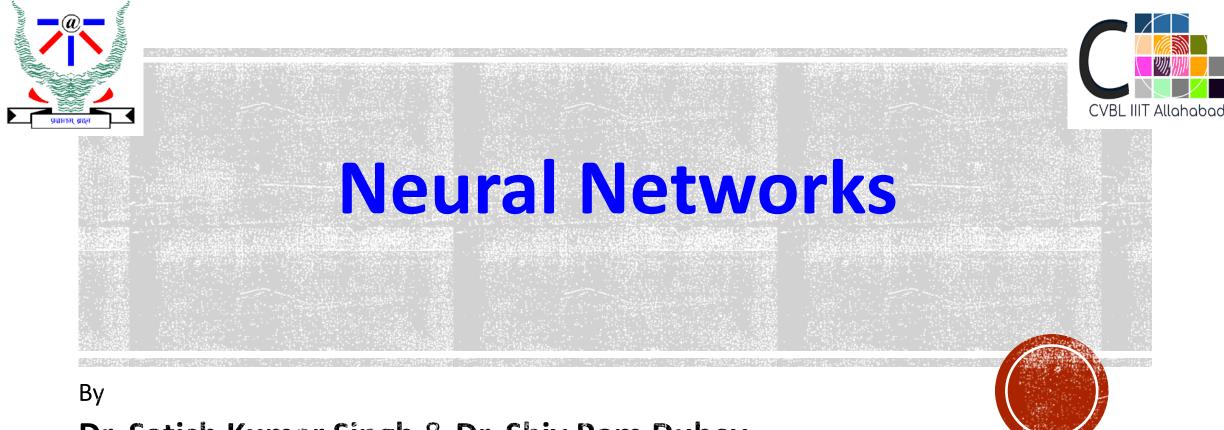
Indian Institute of Information Technology, Allahabad



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Computer Vision and Biometrics Lab
Department of Information Technology
Indian Institute of Information Technology, Allahabad

TEAM

Computer Vision and Biometrics Lab (CVBL)

Department of Information Technology

Indian Institute of Information Technology Allahabad

Course Instructors

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WE HAVE LEARNED SO FOR IN THIS MODULE

Image features and categorization

Choosing right features
Object, Scene, Action, etc.

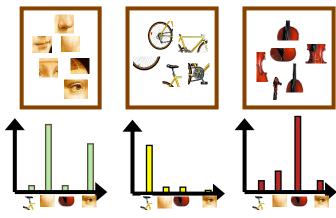
Bag-of-visual-words

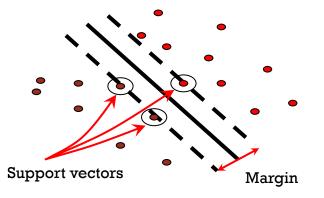
Extract local features
Learn "visual vocabulary"
Quantize features using visual vocabulary
Represent by frequencies of "visual words"

Classifiers

Nearest neighbor, KNN, Linear classifier, SVM, Non-linear SVM, Multi-class SVM, Softmax classifier









TODAY'S CLASS

Optimization

Gradient Descent & Back propagation

Update rule

Neural networks



OPTIMIZATION

Optimization is the process of finding the set of parameters W that minimize the loss function.

Strategy #1:First very bad idea solution: Random search:

Simply try out many different random weights and keep track of what works best.

Strategy #2: Random local search:

Start out with a random W, generate random changes δW to it and if the loss at the changed $W+\delta W$ is lower, we will perform an update.

Strategy #3: Following the gradients:

There is no need to randomly search for a good direction: this direction is related to the gradient of the loss function.



Source: http://cs231n.github.io

GRADIENT DESCENT

The procedure of repeatedly evaluating the gradient of loss function and then performing a parameter update.

Vanilla (Original) Gradient Descent:

```
while True:
    weights_grad = evaluate_gradient(loss_fun, data, weights)
    weights += - step_size * weights_grad # perform parameter update
```

Mini-batch Gradient Descent (MGD):

```
while True:
    data_batch = sample_training_data(data, 256) # sample 256 examples
    weights_grad = evaluate_gradient(loss_fun, data_batch, weights)
    weights += - step_size * weights_grad # perform parameter update
```

Stochastic Gradient Descent (SGD):

Special case of MGD when mini-batch contains only a single example



Interpretation. Derivatives indicate the rate of change of a function with respect to that variable surrounding an infinitesimally small region near a particular point:

$$rac{df(x)}{dx} = \lim_{h o 0} rac{f(x+h) - f(x)}{h}$$



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$$f(x,y) = x + y \hspace{1cm}
ightarrow \hspace{1cm} rac{\partial f}{\partial x} = \hspace{1cm} rac{\partial f}{\partial y} = \hspace{1cm}$$



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$$f(x,y) = x + y \qquad \qquad o \qquad rac{\partial f}{\partial x} = 1 \qquad \qquad rac{\partial f}{\partial y} = 1$$

$$f(x,y)=xy \qquad o \qquad rac{\partial f}{\partial x}= \qquad \qquad rac{\partial f}{\partial y}= 0$$



$$rac{df(x)}{dx} = \lim_{h o 0} rac{f(x+h) - f(x)}{h}$$

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$$f(x,y)=xy \qquad \qquad o \qquad rac{\partial f}{\partial x}=y \qquad \qquad rac{\partial f}{\partial y}=x$$

$$f(x,y) = \max(x,y) \qquad o \qquad rac{\partial f}{\partial x} = \qquad \qquad rac{\partial f}{\partial y} =$$



$$rac{df(x)}{dx} = \lim_{h o 0} rac{f(x+h) - f(x)}{h}$$

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$$f(x,y)=xy \qquad \qquad o \qquad rac{\partial f}{\partial x}=y \qquad \qquad rac{\partial f}{\partial y}=x$$

$$f(x,y) = \max(x,y) \qquad o \qquad rac{\partial f}{\partial x} = \mathbb{1}(x>=y) \qquad rac{\partial f}{\partial y} = \mathbb{1}(y>=x)$$



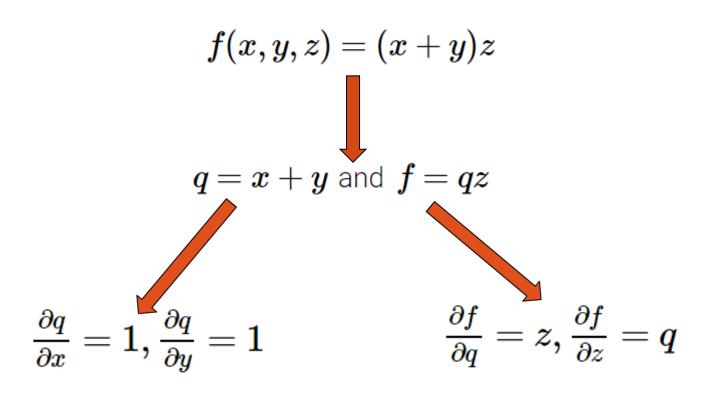
$$f(x,y,z) = (x+y)z$$





$$f(x,y,z)=(x+y)z$$
 $q=x+y$ and $f=qz$ $rac{\partial q}{\partial x}=1, rac{\partial q}{\partial y}=1$ $rac{\partial f}{\partial q}=z, rac{\partial f}{\partial z}=q$



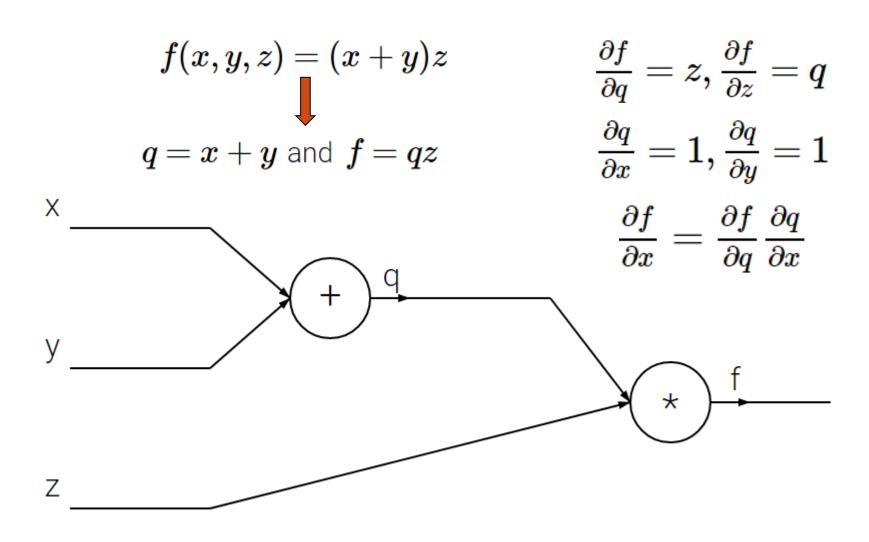


Chain rule: $\frac{\partial f}{\partial x} = \frac{\partial f}{\partial a} \frac{\partial q}{\partial x}$

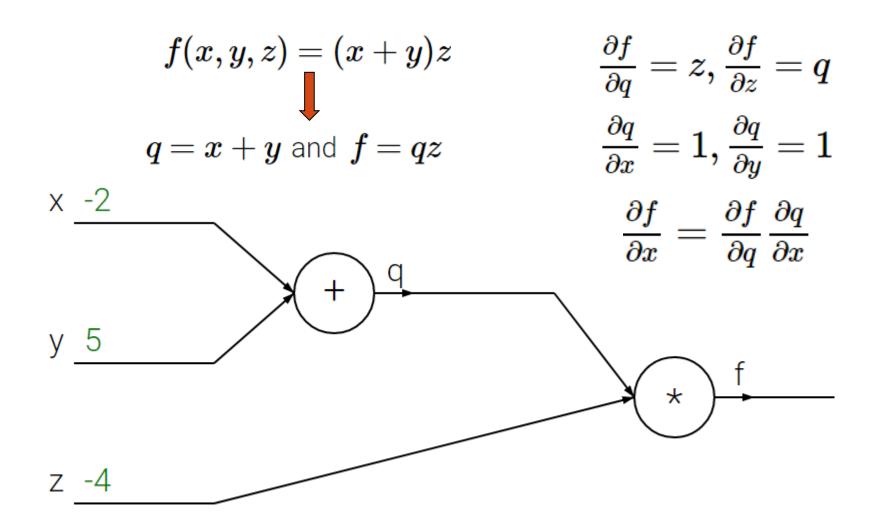


$$egin{align} rac{\partial f}{\partial q} &= z, rac{\partial f}{\partial z} &= q \ rac{\partial q}{\partial x} &= 1, rac{\partial q}{\partial y} &= 1 \ rac{\partial f}{\partial x} &= rac{\partial f}{\partial q} rac{\partial q}{\partial x} \end{aligned}$$

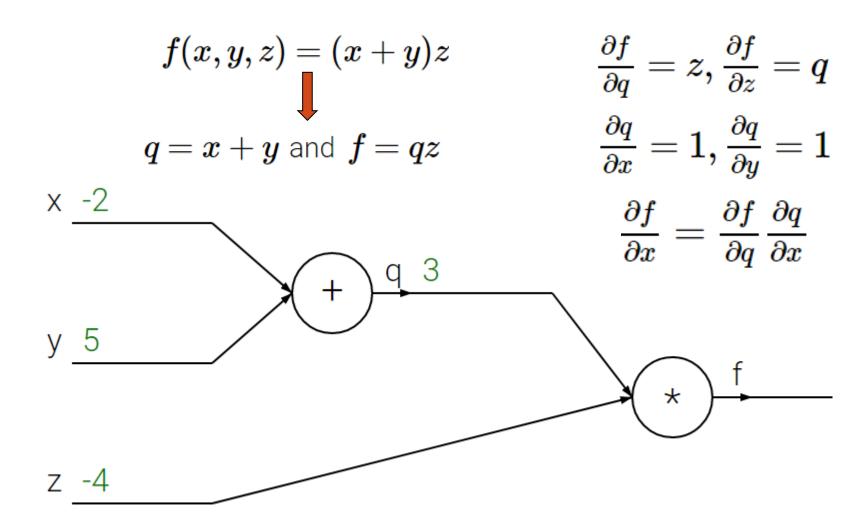




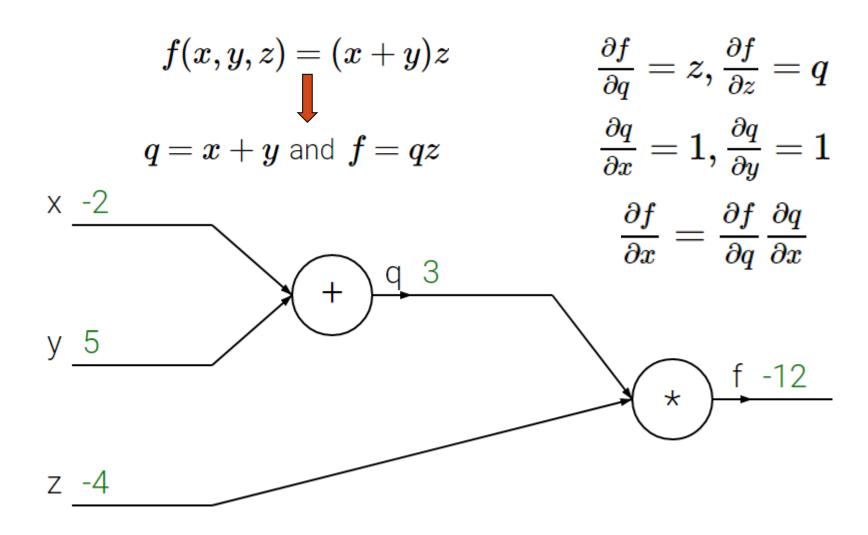




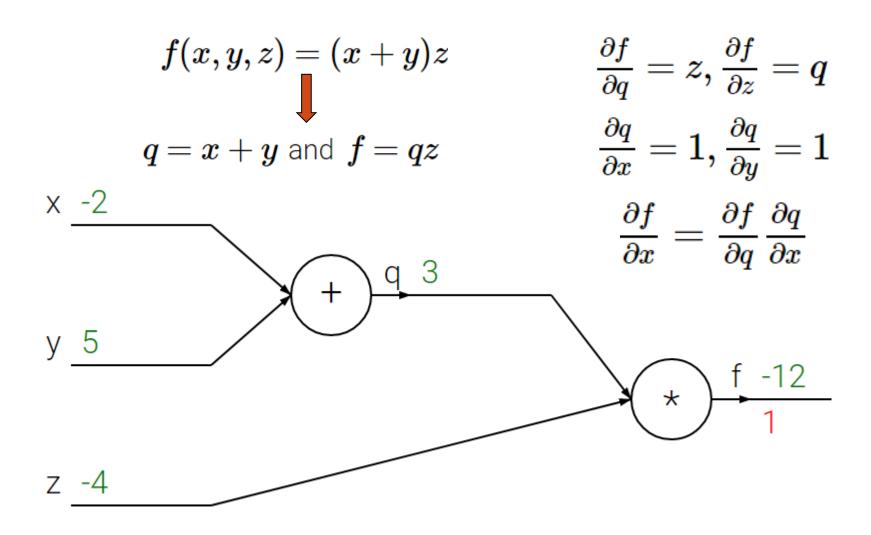




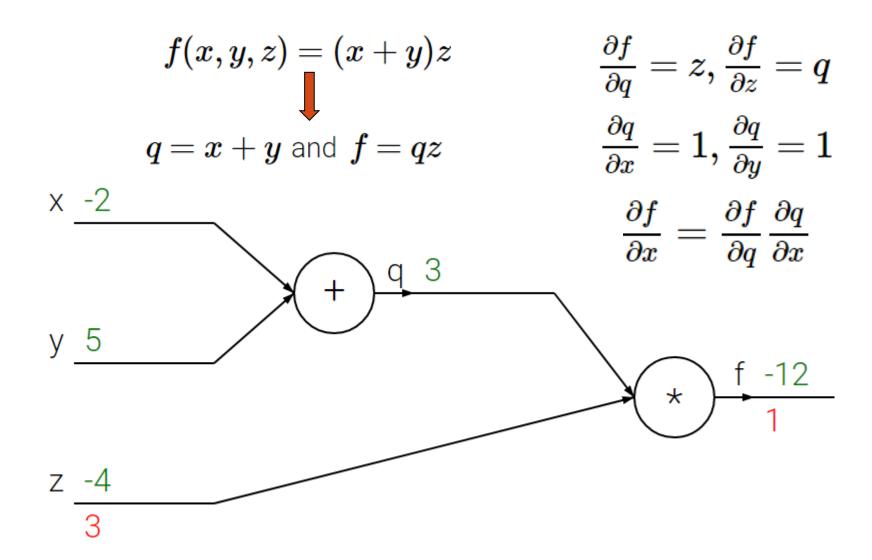




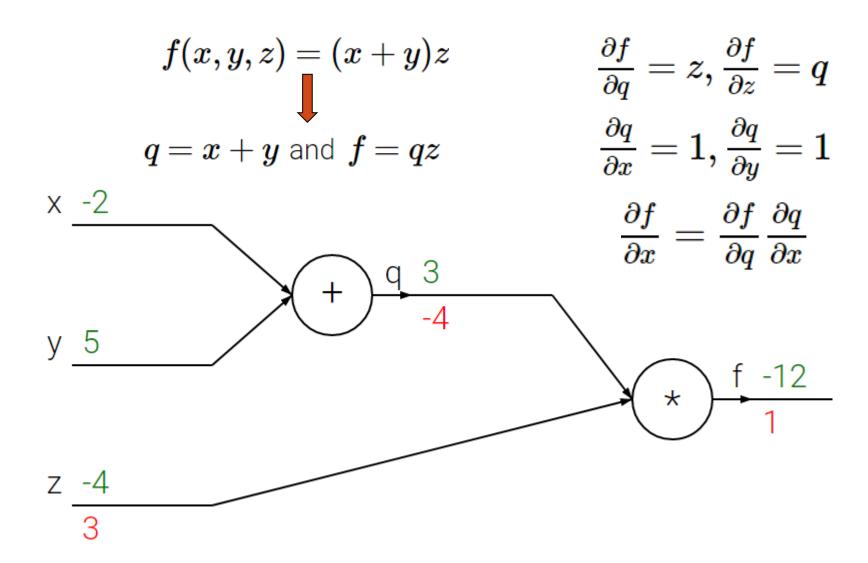




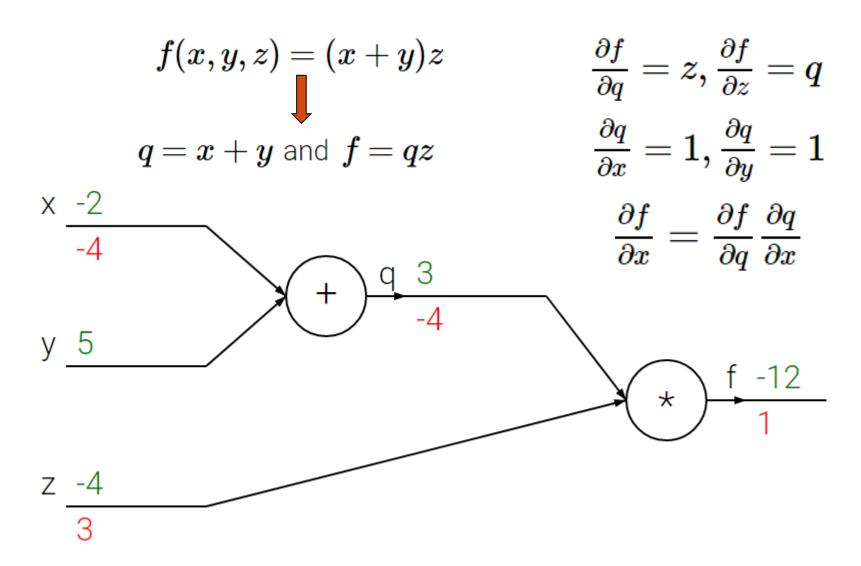




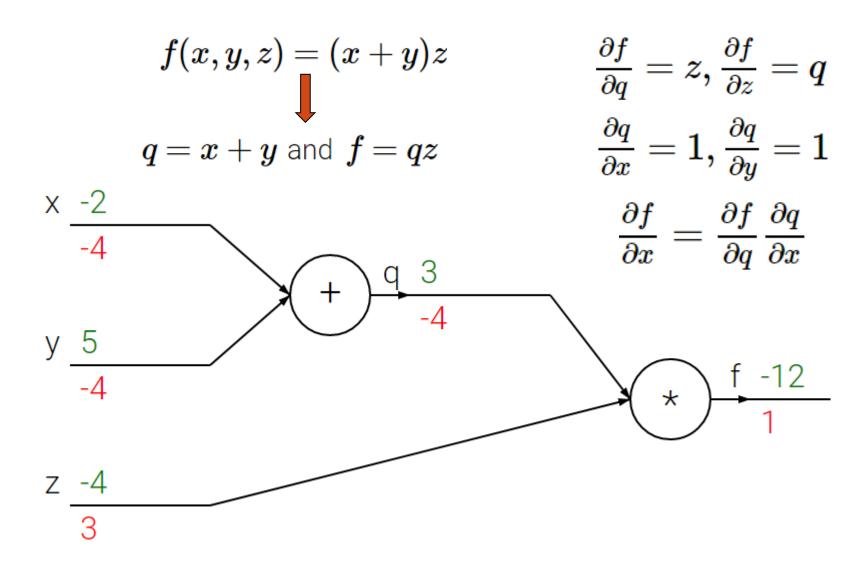




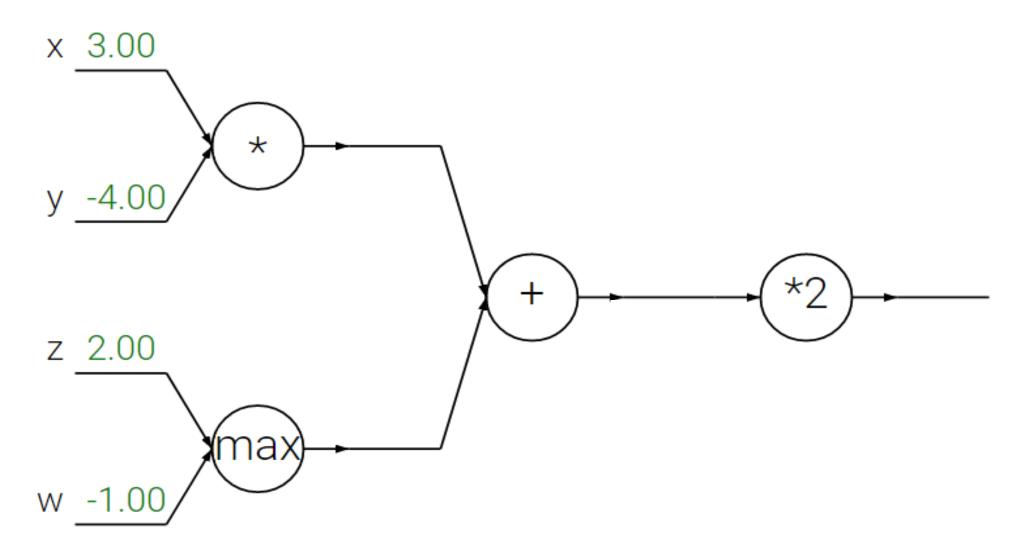




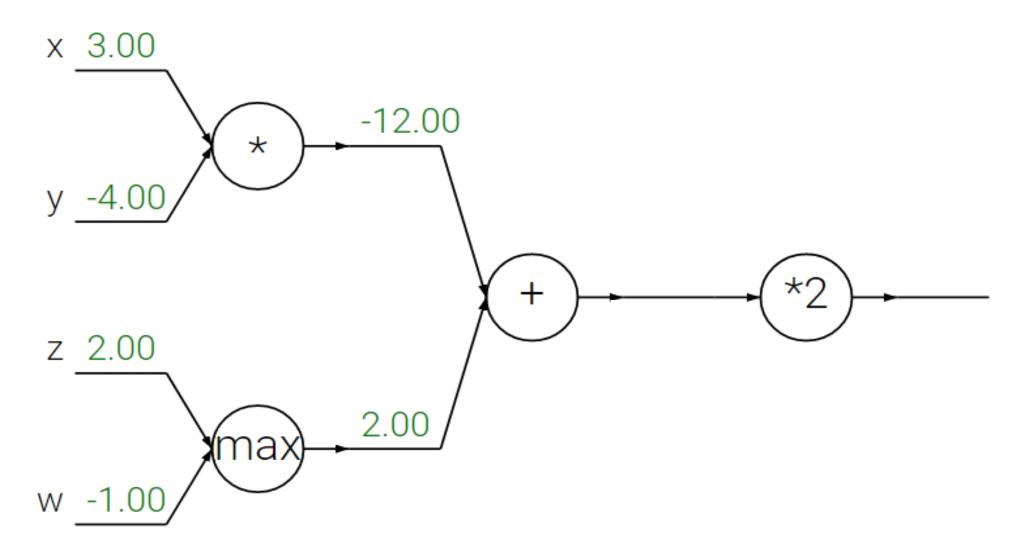




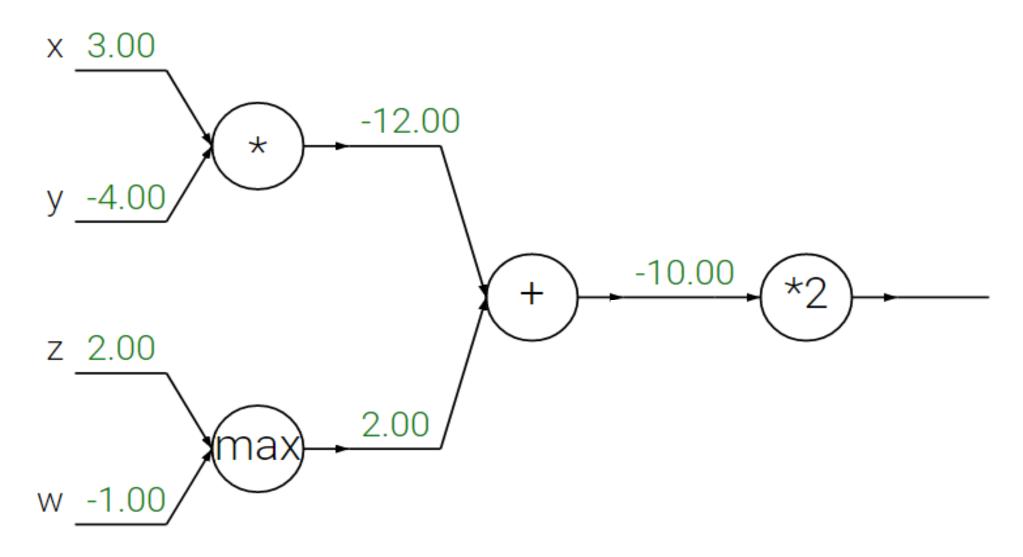




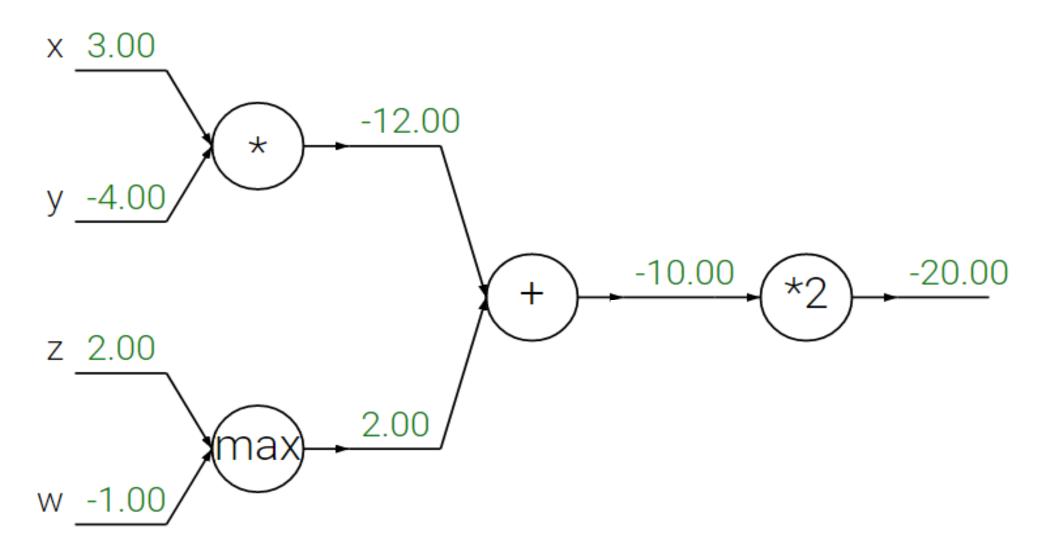




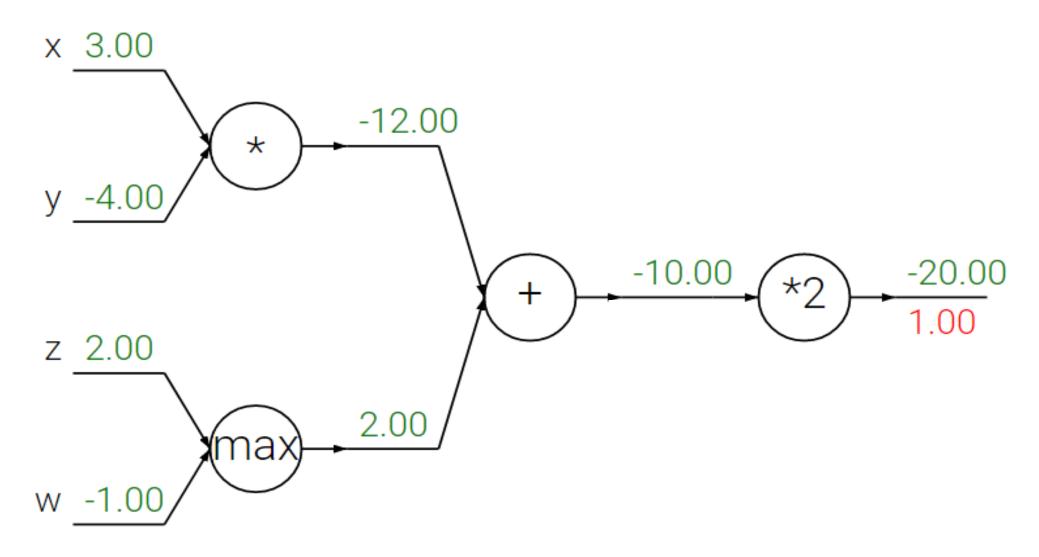




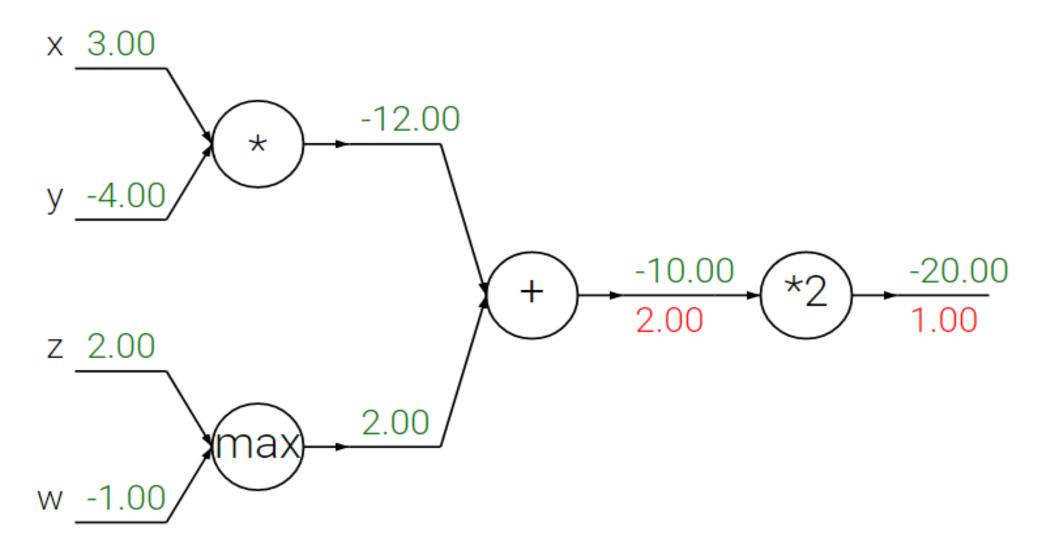




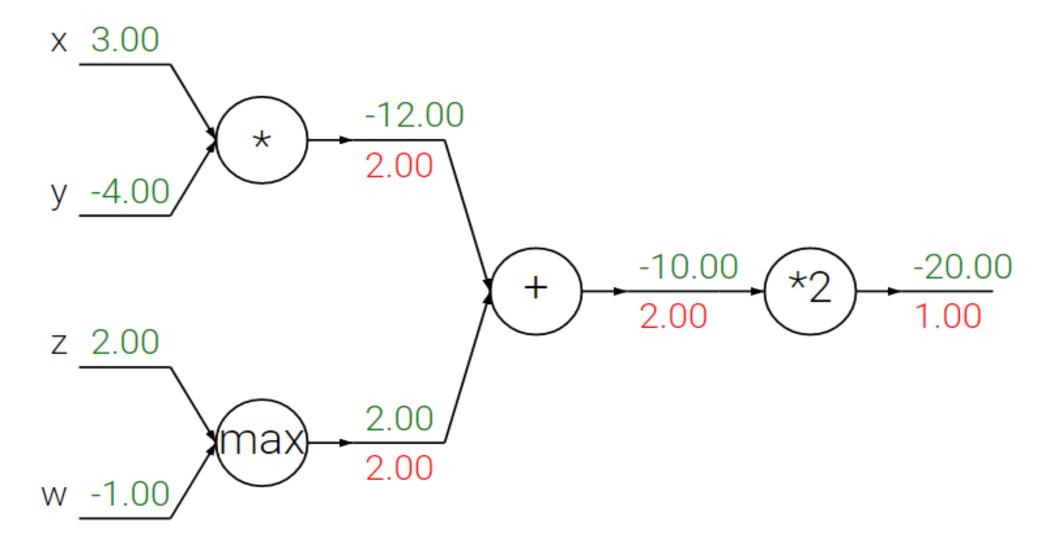




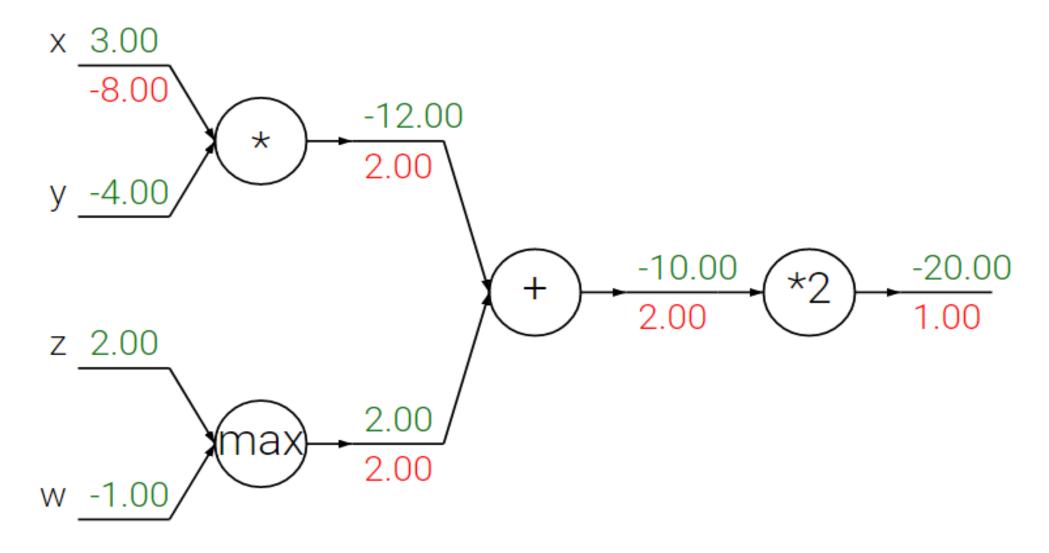






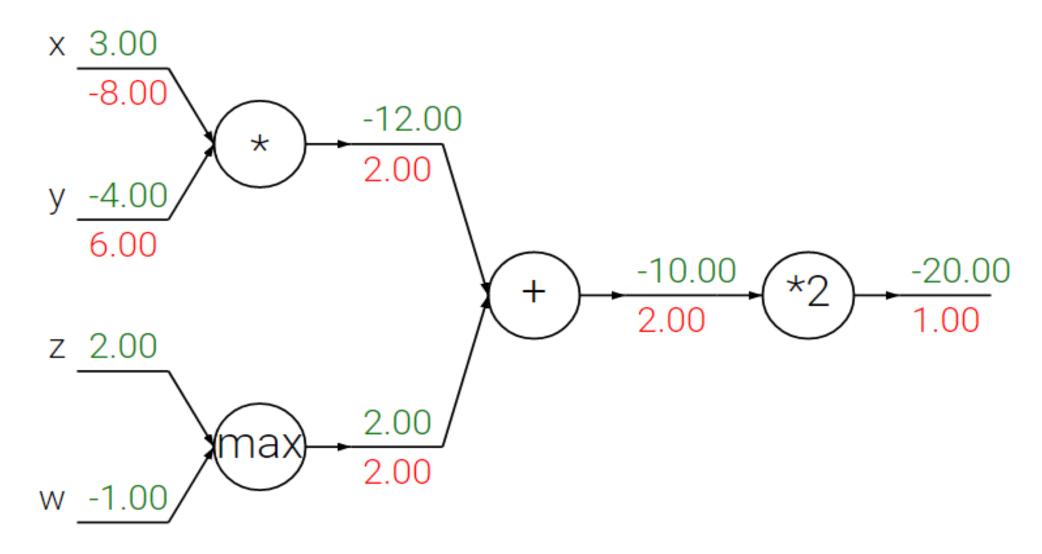






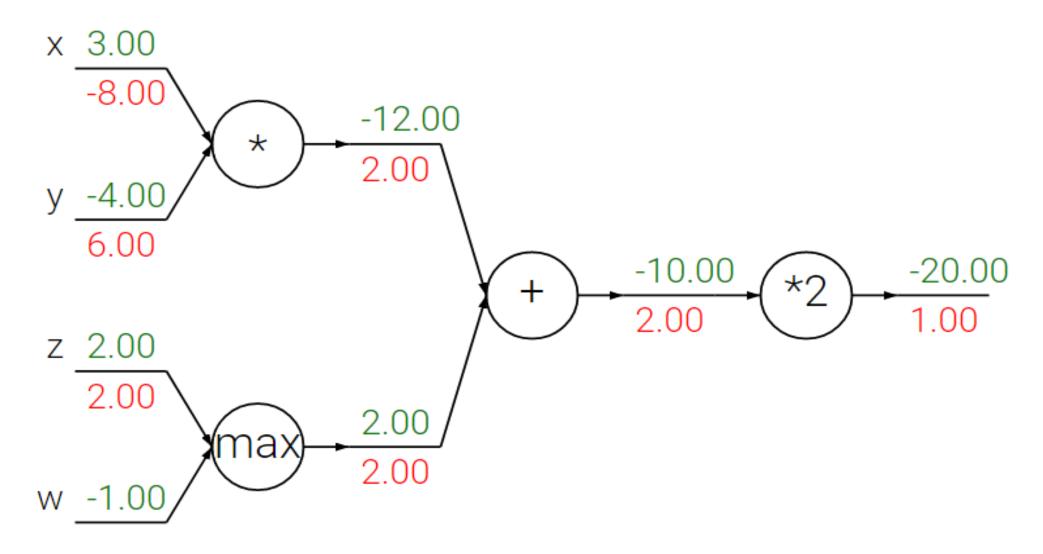


FORWARD AND BACKWARD PASS



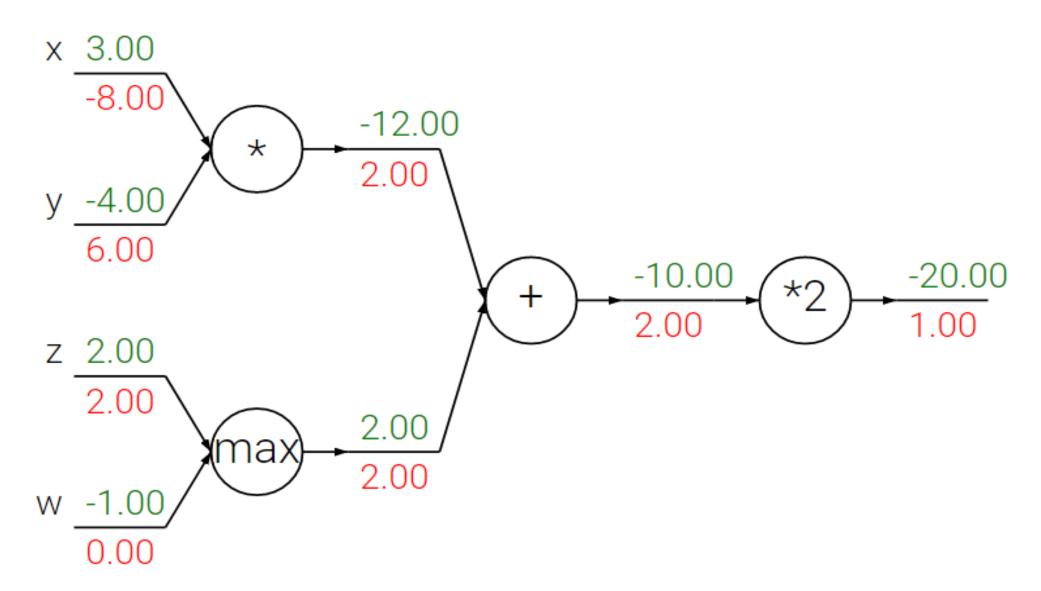


FORWARD AND BACKWARD PASS





FORWARD AND BACKWARD PASS

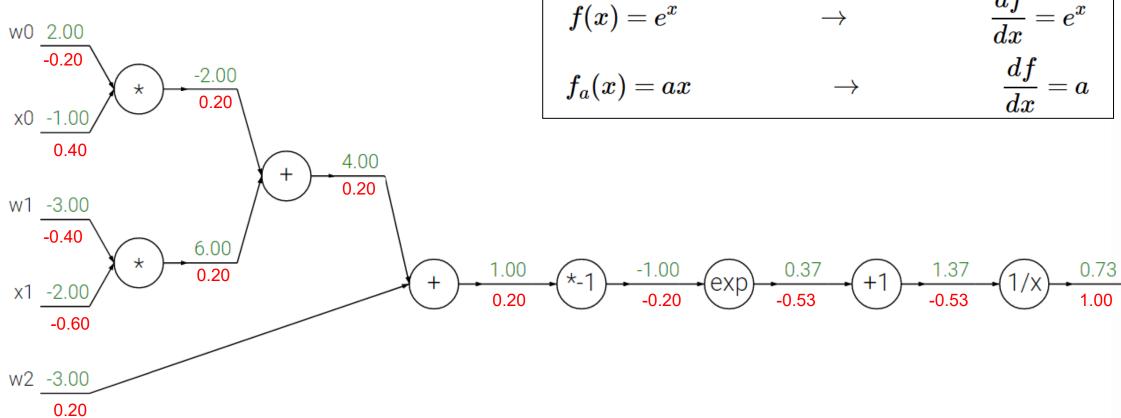




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SIGMOID EXAMPLE

$$f(w,x)=rac{1}{1+e^{-(w_0x_0+w_1x_1+w_2)}}$$



SVM loss function for a single datapoint (without regularization):

$$L_i = \sum_{j
eq y_i} \left[\max(0, w_j^T x_i - w_{y_i}^T x_i + \Delta)
ight]$$



Source: http://cs231n.github.io

SVM loss function for a single datapoint (without regularization):

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ight] \ L_i = \sum_{j
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Gradient w.r.t. w_{y_i} :

$$abla_{w_{y_i}}L_i = -\left(\sum_{j
eq y_i} 1(w_j^T x_i - w_{y_i}^T x_i + \Delta > 0)
ight)x_i$$



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ight)x_i$$

Count of the number of classes that didn't meet the desired margin



SVM loss function for a single datapoint (without regularization):

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Gradient w.r.t. w_{y_i} :

$$egin{aligned}
abla_{w_{y_i}} L_i = -\left(\sum_{j
eq y_i} \mathbb{1}(w_j^T x_i - w_{y_i}^T x_i + \Delta > 0)
ight) x_i \end{aligned}$$

Count of the number of classes that didn't meet the desired margin

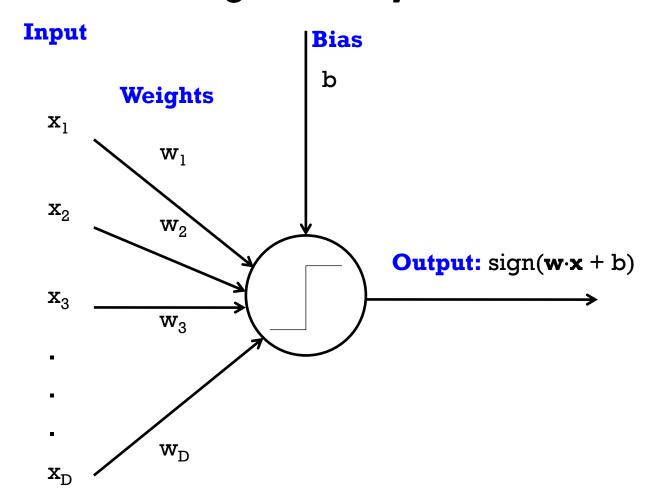
Gradient for the other rows where $j \neq y_i$:

$$abla_{w_j}L_i=1(w_j^Tx_i-w_{y_i}^Tx_i+\Delta>0)x_i$$



PERCEPTRON

Supervised learning of binary classifier





Binary Softmax classifier (Logistic Regression)

$$\sigma(\sum_i w_i x_i + b)$$



Source: http://cs231n.github.io

Binary Softmax classifier (Logistic Regression)

$$\sigma(\sum_i w_i x_i + b)$$

Probability of one of the classes:

$$P(y_i = 1 \mid x_i; w)$$



Binary Softmax classifier (Logistic Regression)

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Probability of one of the classes:

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Probability of the other class would be:

$$P(y_i = 0 \mid x_i; w) = 1 - P(y_i = 1 \mid x_i; w)$$



Source: http://cs231n.github.io

Binary Softmax classifier (Logistic Regression)

$$\sigma(\sum_i w_i x_i + b)$$

Probability of one of the classes:

$$P(y_i = 1 \mid x_i; w)$$

Probability of the other class would be:

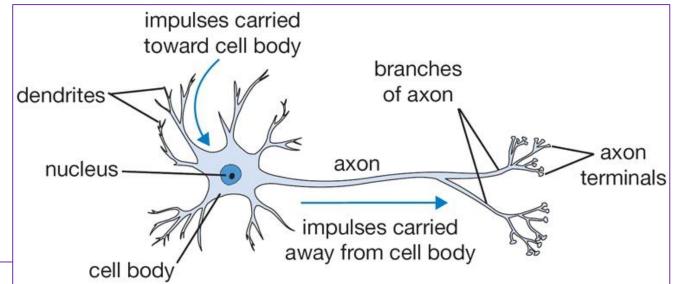
$$P(y_i = 0 \mid x_i; w) = 1 - P(y_i = 1 \mid x_i; w)$$

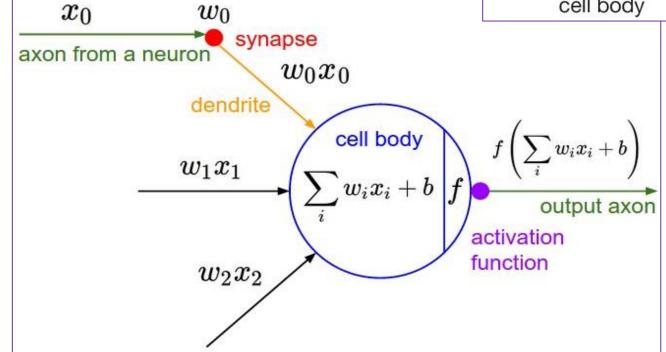
Binary SVM classifier:

Alternatively, we could attach a max-margin hinge loss to the output of the neuron and train it to become a binary Support Vector Machine.



LOOSE INSPIRATION: HUMAN NEURONS

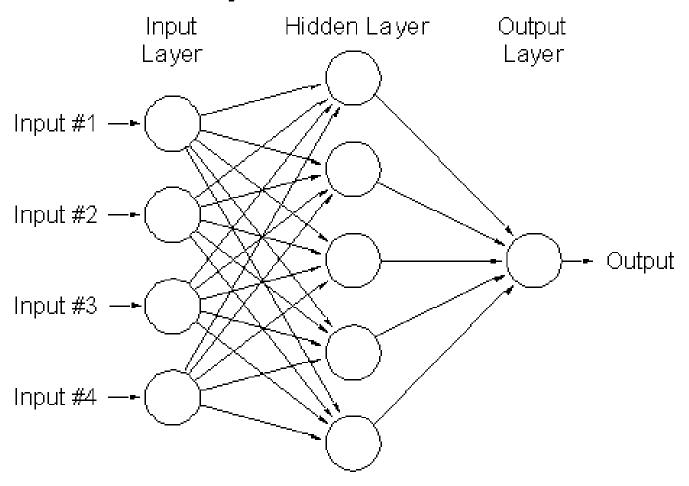






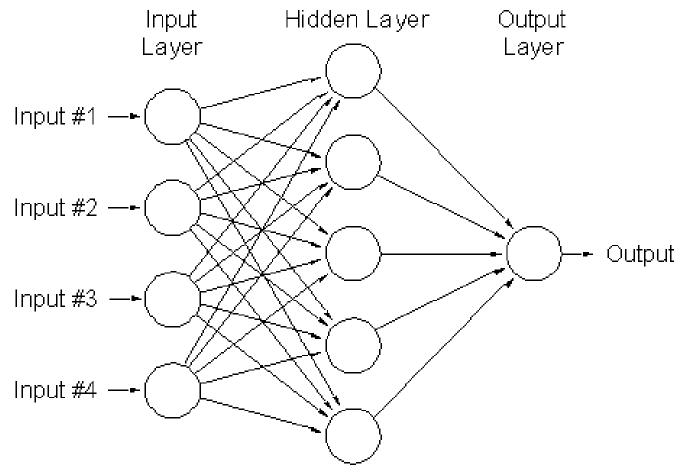
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Network with a hidden layer:





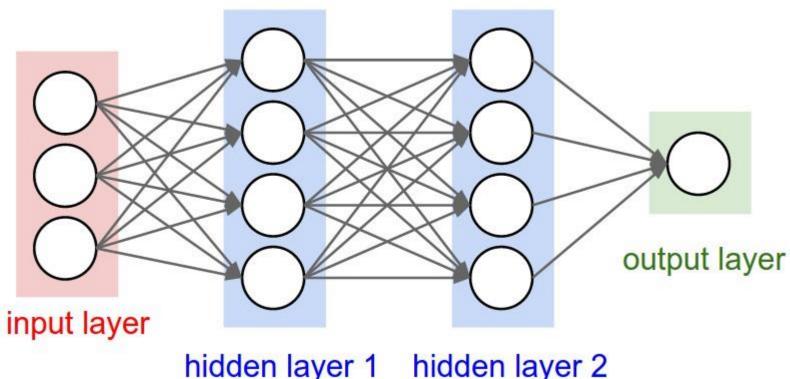
Network with a hidden layer:



 Can represent nonlinear functions (provided each perceptron has a nonlinearity)



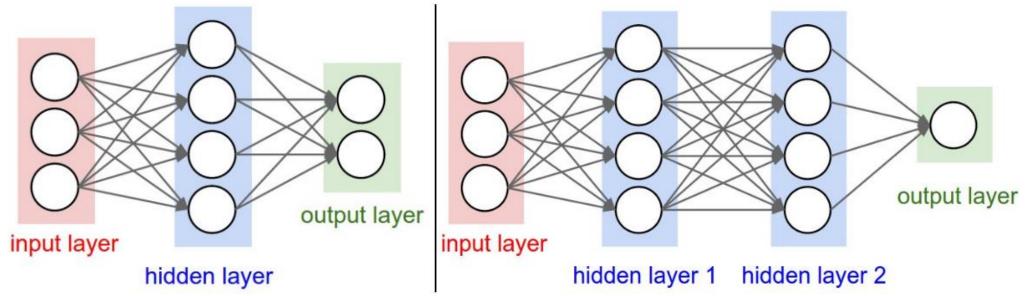
Beyond a single hidden layer:



hidden layer 1 hidden layer 2



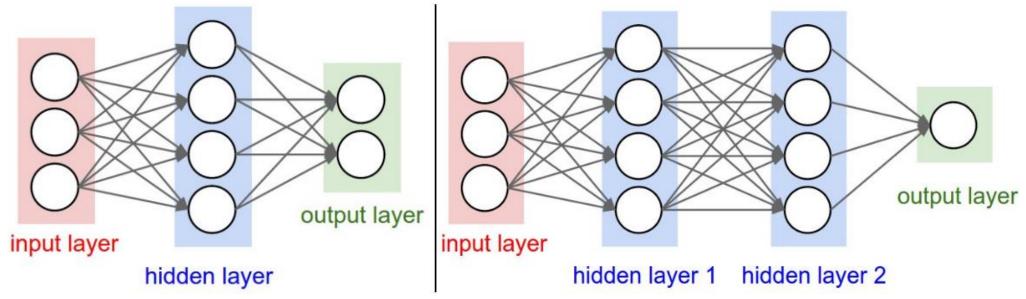
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First network (left):

No. of neurons (not counting the inputs):

No. of learnable parameters:

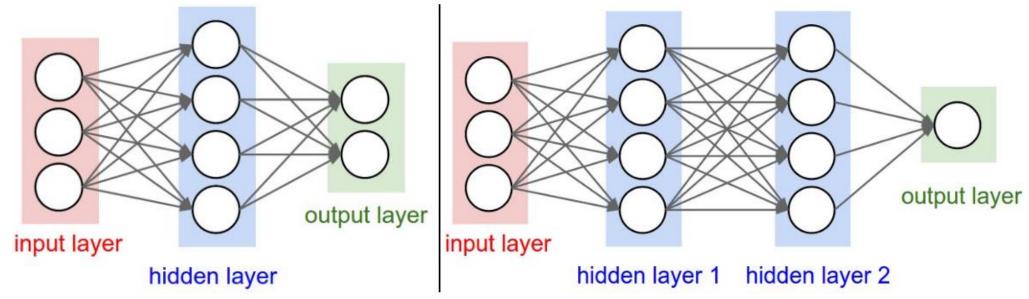


First network (left):

No. of neurons (not counting the inputs): 4 + 2 = 6

No. of learnable parameters:

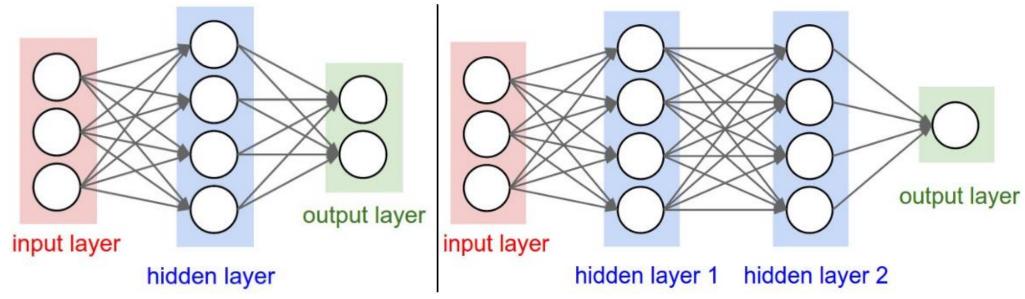




First network (left):

No. of neurons (not counting the inputs): 4 + 2 = 6No. of learnable parameters: $[3 \times 4] + [4 \times 2] = 20$ weights + 4 + 2 = 6 biases = 26.





First network (left):

No. of neurons (not counting the inputs): 4 + 2 = 6

No. of learnable parameters: $[3 \times 4] + [4 \times 2] = 20$ weights +

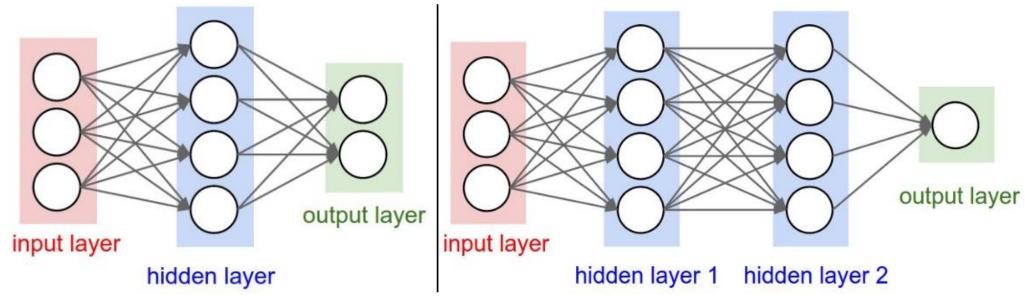
4 + 2 = 6 biases = 26.

Second network (right):

No. of neurons (not counting the inputs):

No. of learnable parameters:





First network (left):

No. of neurons (not counting the inputs): 4 + 2 = 6

No. of learnable parameters: $[3 \times 4] + [4 \times 2] = 20$ weights +

4 + 2 = 6 biases = 26.

Second network (right):

No. of neurons (not counting the inputs): 4 + 4 + 1 = 9

No. of learnable parameters: [3x4]+[4x4]+[4x1] = 32 weights +

$$4 + 4 + 1 = 9$$
 biases = 41.

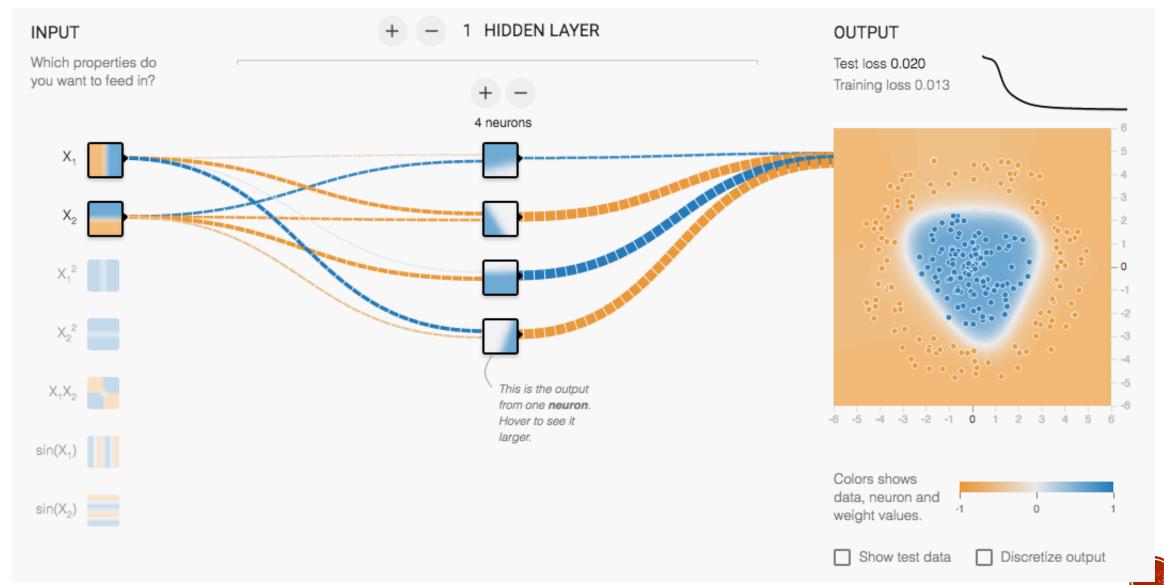


3 hidden neurons 6 hidden neurons 20 hidden neurons



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MULTI-LAYER NETWORK DEMO



TRAINING OF MULTI-LAYER NETWORKS

 Find network weights to minimize the error between true and estimated outputs of training examples:

$$E(\mathbf{w}) = \sum_{j=1}^{N} (y_j - f_{\mathbf{w}}(\mathbf{x}_j))^2$$



TRAINING OF MULTI-LAYER NETWORKS

 Find network weights to minimize the error between true and estimated outputs of training examples:

$$E(\mathbf{w}) = \sum_{j=1}^{N} (y_j - f_{\mathbf{w}}(\mathbf{x}_j))^2$$

Update weights by **gradient descent:** $\mathbf{w} \leftarrow \mathbf{w} - \alpha \frac{\partial E}{\partial \mathbf{w}}$



TRAINING OF MULTI-LAYER NETWORKS

 Find network weights to minimize the error between true and estimated outputs of training examples:

$$E(\mathbf{w}) = \sum_{j=1}^{N} (y_j - f_{\mathbf{w}}(\mathbf{x}_j))^2$$

- Update weights by **gradient descent:** $\mathbf{w} \leftarrow \mathbf{w} \alpha \frac{\partial E}{\partial \mathbf{w}}$
- Back-propagation: gradients are computed in the direction from output to input layers and combined using chain rule



NEURAL NETWORKS: PROS AND CONS

Pros

- Flexible and general function approximation framework
- Can build extremely powerful models by adding more layers



NEURAL NETWORKS: PROS AND CONS

Pros

- Flexible and general function approximation framework
- Can build extremely powerful models by adding more layers

Cons

- Hard to analyze theoretically (e.g., training is prone to local optima)
- Huge amount of training data, computing power may be required to get good performance
- The space of implementation choices are huge (network architectures, parameters)



ACKNOWLEDGEMENT

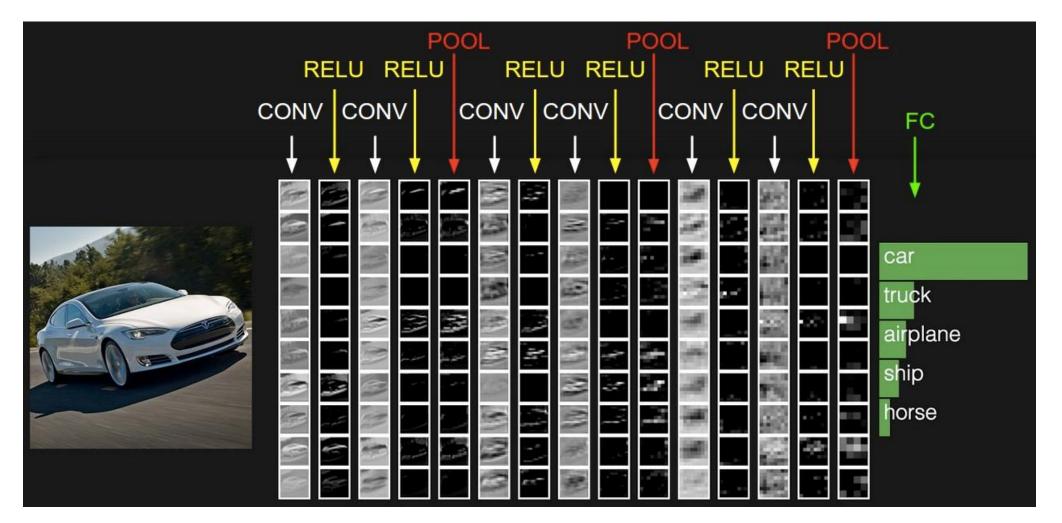
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- Convolutional Neural Networks for Visual Recognition, Stanford University
- Deep Learning, Stanford University
- Introduction to Deep Learning, University of Illinois at Urbana-Champaign
- Introduction to Deep Learning, Carnegie Mellon University
- Natural Language Processing with Deep Learning, Stanford University
- And Many More Publicly Available Resources



NEXT LECTURE

Convolutional Neural Networks





Questions?

